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1.5Linearization of the valve shows that $v=4v_3 0 u$.

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$D(q - 1)A(q - 1) [-T(t) \quad (t \sim +1)]$ (3.161) and the parameter adaptation algorithm satisfying the passivity condition will take the form:
 $(t \hat{+} 1) = (t) \hat{+} F (t) (t+1)$ (3.162) The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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